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.libPaths("C:/R Code")
source("func_express.R") # symbolic regression function processing
source("LiftingSchemeJPEG.R") # JPEG package
source("PenalizedJPEG.R") # Penalized JPEG package

library(MASS)
library(stringr)
require(splines)
library(minpack.lm)
library(gmm)
library(Deriv)
library(np)

emptylist<-function(q,init=NA){
  mylist.names<-paste0("c",1:q,sep="")
  if (length(init)>=q) {
    mylist <- as.list(init[1:q])
  }
  else {
    mylist <- as.list(c(init,rep(0,q-length(init))))
  }
  names(mylist)<-mylist.names
  return(mylist)
}

#----- GMM:Global.penalization choice -----
Penalization.JPEG.GMMReg<-function(myformula, zformula, data,b0,
Level=NaN, UpToLevel=NaN, gamma=Inf, lambda = NaN) {

  #----- PREPARING THE INPUT SPACE -----
  data$index = 1:nrow(data)
  data=data[with(data, order(t)),]
  out<-exp.f(myformula,data)
  Y = as.matrix(data[,names(out$y)])
  X = as.matrix(data[,names(out$x)])
  t = as.matrix(data[,names(out$m[[1]])])

  # Projection formula  $[Z \cdot \text{inv}(Z'Z) \cdot t(Z)] \cdot [\text{Signal-yhat}]$ 
  # Z = [z, m(t)]; p = Signal-yhat
  Projection = paste0("p~",Reduce(paste,
deparse(zformula[[3]])),sep=" ",collapse="")
  print(sprintf("projection=%s",Projection))
  Projection = as.formula(Projection)

  z.out<-exp.f(zformula,data)
  Z = as.matrix(data[,names(z.out$x)])
  z.names=names(z.out$x)[!(names(z.out$x)%in%names(out$x))]
  sub.Z = as.matrix(data[,z.names])

  #----- INITIALIZING THE PARAMETERS -----
  alpha = 0.001
  n=nrow(data)

  if (is.nan(Level)) {

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    Level = ceiling(log(n/log(2)))
}

if (is.nan(UpToLevel)){
  UpToLevel = min(Level-1, 7+(n>=2000))
}

b=b0

X.Grid = t
Signal = as.matrix(Y-X%%as.matrix(b))

temp = main.filter.X.Grid(y=Signal, X.Grid=X.Grid, Level)
my.X.Grid = temp$X.Grid

coeff=temp$y

#-----
iter = 0
gap = Inf
n = length(Signal)
new.alpha=NULL
max.coeff=max(abs(coeff))
min.coeff=min(abs(coeff))
print(sprintf("max.coeff=%f, lambda/alpha=%f,
gamma*lambda=%f",max.coeff, lambda/alpha, gamma*lambda))

# print(coeff)

min.gamma = min.coeff / lambda

OK = TRUE
gap = Inf
while ((iter < 1000) & OK & (gap>0.0001)) {
  # print("inner loop")
  gap = Inf
  Xt.res = NULL
  old.Xt.res = NULL
  Linear.Xt.res = NULL
  old.Linear.Xt.res = NULL
  iter.inner=0

  #-----
  # yhat is the prediction obtained as the inverse-transform of the
  coefficient vector (coeff)
  # by using the irregular grid (my.X.Grid)
  yhat = inv.main.filter.X.Grid(coeff, my.X.Grid, Level)$y
  #-----
  residual = Signal - yhat

  Z.residual=sub.Z%%inv(t(sub.Z)%%sub.Z)%%t(sub.Z)%%residual

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#-----Equation (3.10) -----
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# Let Psi_I and t(Psi_I) be the JPEG-inverse transform operator and
its transpose, respectively.
# By using the transposed-inverse-transform (inv.t), we calculate
Xt.res=t(Psi_I)*residual
Xt.res = inv.t(residual, X.Grid=X.Grid, Level = Level)
#-----
-----

Linear.Xt.res = t(X)%%Z.residual

GMMObjective<-function(residual){
  g1 = 1/n*as.matrix(t(Z)%%residual)
  return(n*t(g1)%%pinv(1/n*t(Z)%%Z)%%g1)
}

# ----- EVALUATION OF THE PENALIZED gmm OBJECTIVE FUNCTION ---
-----
object.fun = 1/(2*n)*GMMObjective(residual) +
sum(MCP.penalty(abs(coeff),lambda, alpha, gamma))

print(sprintf("obj=%f,gmmobj=%f",object.fun,GMMObjective(residual)))

old.object.fun = object.fun
old.coeff = coeff
old.b = b
old.Signal = Signal
old.Xt.res = Xt.res
old.Linear.Xt.res = Linear.Xt.res
old.yhat = yhat

inner.iter = 0
if (iter==0){
  alpha = alpha
} else{
  alpha = sqrt(new.alpha)
}

alpha = max(alpha,1/gamma+0.000001)

repeat {
  Update = coeff+rep(1/(alpha*n),length(Xt.res))*Xt.res
  Update.b = b+rep(1/(alpha*n),length(Linear.Xt.res))*Linear.Xt.res

  # ----- BEGIN OF JPEG coefficients update (MCP
thresholding)
  coeff = S.alpha.Threshold(Update, lambda, alpha, gamma)
  # ----- END OF JPEG coefficients update -----
--

b = Update.b
yhat = inv.main.filter.X.Grid(coeff, my.X.Grid, Level)$y

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b=inv(t(Z)%*%X)%*%t(Z)%*%as.matrix(Y-yhat)

Signal = as.matrix(Y-X%*%as.matrix(b))

residual = Signal - yhat

object.fun = 1/(2*n)*GMMObjective(residual) +
sum(MCP.penalty(abs(coeff),lambda, alpha, gamma))

d=c(coeff-old.coeff, b-old.b)
gap = max(abs(d))

iter.inner = iter.inner + 1

OK = (object.fun < old.object.fun)
if ((inner.iter > 100)| OK) {
  Z.residual=sub.Z%*%inv(t(sub.Z)%*%sub.Z)%*%t(sub.Z)%*%residual
  Xt.res = inv.t(residual, X.Grid=X.Grid, Level = Level)
  Linear.Xt.res = t(X)%*%Z.residual
  break
} else {
  inner.iter = inner.iter + 1
  alpha = alpha * 1.2;
  coeff = old.coeff
  object.fun = old.object.fun
  Signal = old.Signal
  b = old.b
  Xt.res = old.Xt.res
  Linear.Xt.res = old.Linear.Xt.res
  yhat = old.yhat
}
}

if (OK){
  g.a=(-1/n*Xt.res)-(-1/n*old.Xt.res)
  g.b=(-1/n*Linear.Xt.res)-(-1/n*old.Linear.Xt.res)
  g=c(g.a, g.b)
  d=c(coeff-old.coeff, b-old.b)

new.alpha=(t(as.matrix(g))%*%as.matrix(d))/(t(as.matrix(d))%*%as.matrix(d))
)
} else {
  new.alpha = NULL
}

iter = iter + 1
} # ouer while: alpha

print(sprintf("min.gamma=%f, min.coeff=%f", min.gamma, min.coeff))
return(list(b=old.b, coeff=old.coeff, X.Grid=my.X.Grid,
obj.fun=old.object.fun, yhat=old.yhat))
}

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#----- JPEG IV EXAMPLE CODE: BEGIN SIMULATION ---
-----
N=5000 # number of observations

# Generate a trivariate vector of correlated disturbances
v = mvrnorm(N,c(0,0,0),Sigma=matrix(c(1,0.5,-0.25,0.5,1,0.4, -0.25,
0.4, 1),3,3), empirical = TRUE)
eps = rnorm(N,0,1)
ro=0.8; # the correlation of the endogenous covariate with the random
disturbance (in the substantive equation)
# Constructing the covariate t for the bias term function:
t=(1*v[,1]-3*v[,3])/4

# generate an instrumental variable covariate correlated with the bias
term
ro.z=-0.25
z = ro.z*t + sqrt(1-ro.z^2)*rnorm(N,0,1)

# introducing a correlation between the endogenous covariate x2 (which
is v[,2]), Z and epsilon
v[,2]=ro*eps+sqrt(1-ro^2)*v[,2]*rnorm(N,0,1)

# generating a correlation between x2 and t
v[,2] = 0.5*v[,2] + 0.5*z+tanh(t)

# print all correlations:
cor(v[,2],z)
cor(v[,2],eps)
cor(v[,2],t)
cor(z,eps)

data = data.frame(x1= v[,1], x2=v[,2], x3=v[,3],z=z)
#t=(1*v[,1]-3*v[,3])/4
true_b0 = c(1, 1.25)

# the true (bias-free) outcome variable
t0=v[,1]*true_b0(1)+v[,2]*true_b0(2)

# the observed (bias-dependent) outcome variable y
data$y= t0+ 0.8*exp(t)+eps
mydata=data; mydata$t = t

result1 <- tryCatch({ # Store data
  # begin #
  model<-Penalization.JPEG.GMMReg(y~x1+x2+m(t), y~x1+z+m(t), b0=c(12, -
3), data=mydata, lambda=0.001, gamma=Inf)
  model$b
  #i=1
  TRUE
}, error = function(err) {

  print(paste("Model 1: MY_ERROR: ",err))
  return(FALSE)
}, finally = {

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    print("Done")  
  }) # END tryCatch
```